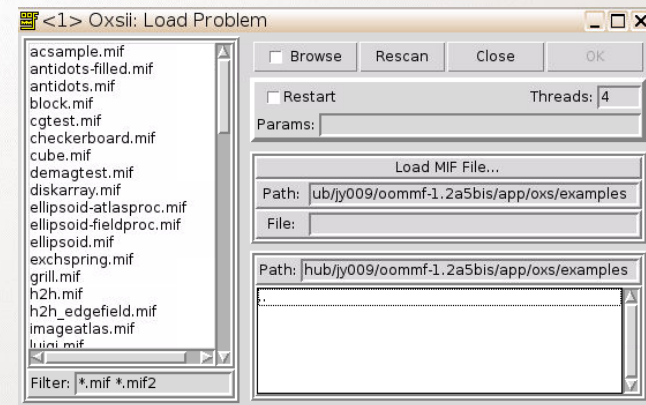
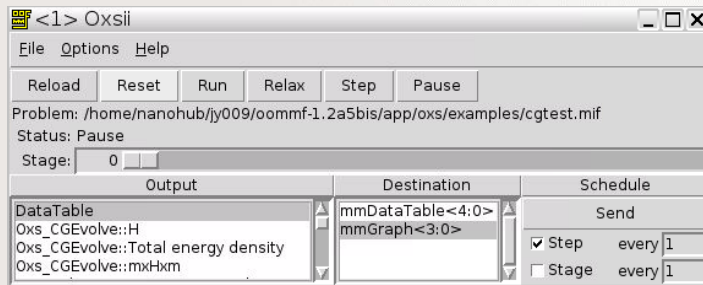
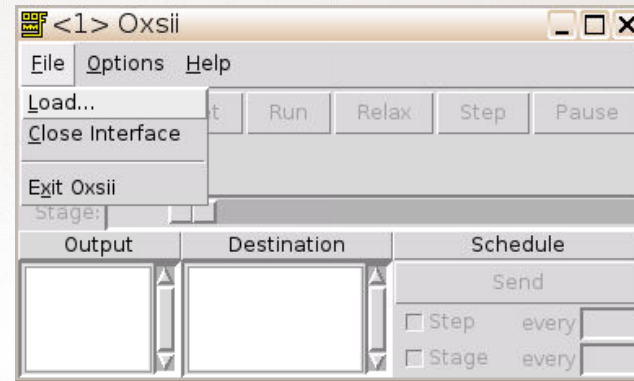
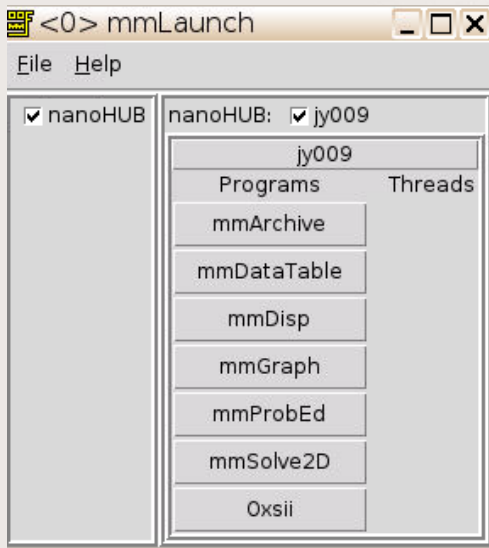


# MIF Generator for OOMMF

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# Oxsii

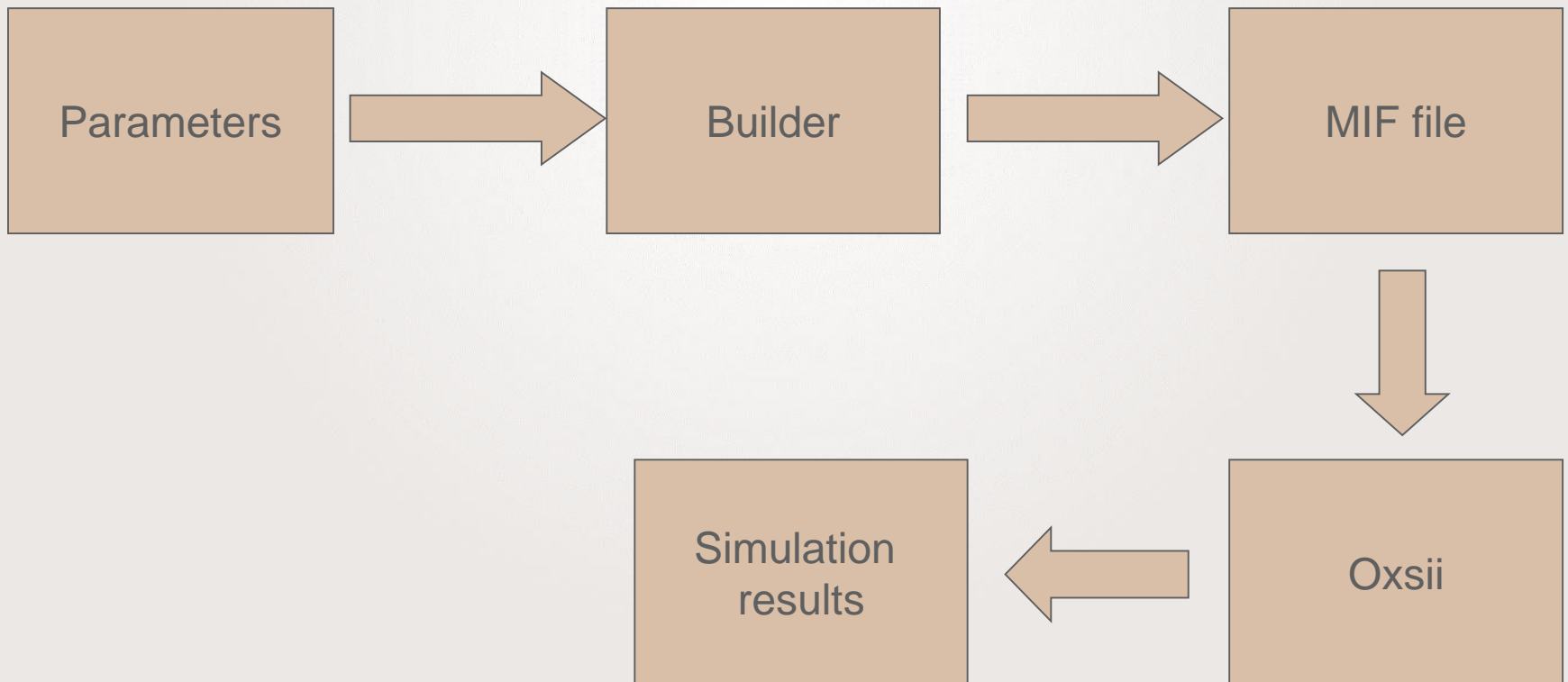


# Difficulties - MIF

- Provided examples are limited
- not user friendly
  - MIF programming is hard
  - User-guideline (Child-class functions)

# Implementation - model builder

- Generate customized model without knowing MIF programming and complete understanding of the user guidelines.
- Use rappture to create a Graphical User Interface.



# Parameters

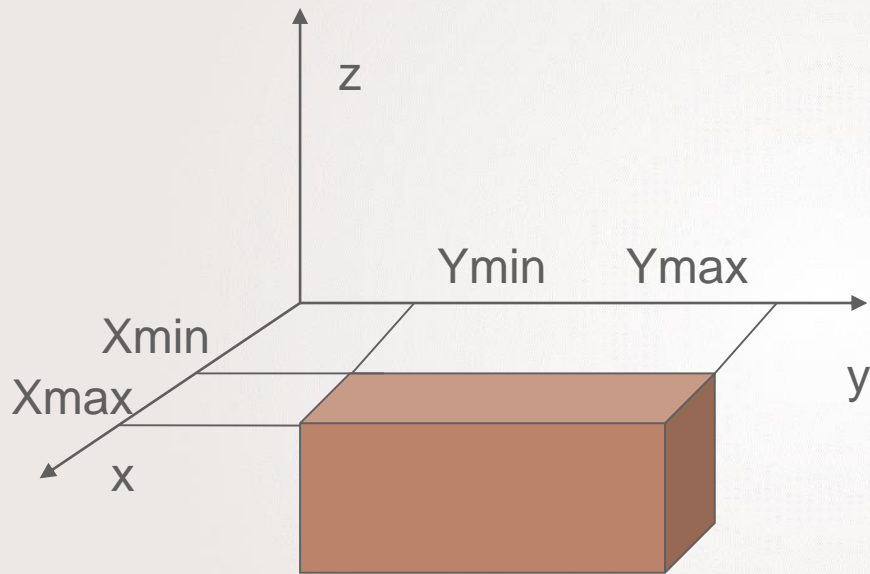
- Dimensions of the model
- Mesh
- Energy functions
- Evolver functions
- Driver functions

# Dimension

- Geometric volumes of spaces
- cube  $(a, b, c)$
- multiple cubes
- ellipsoid

# cube

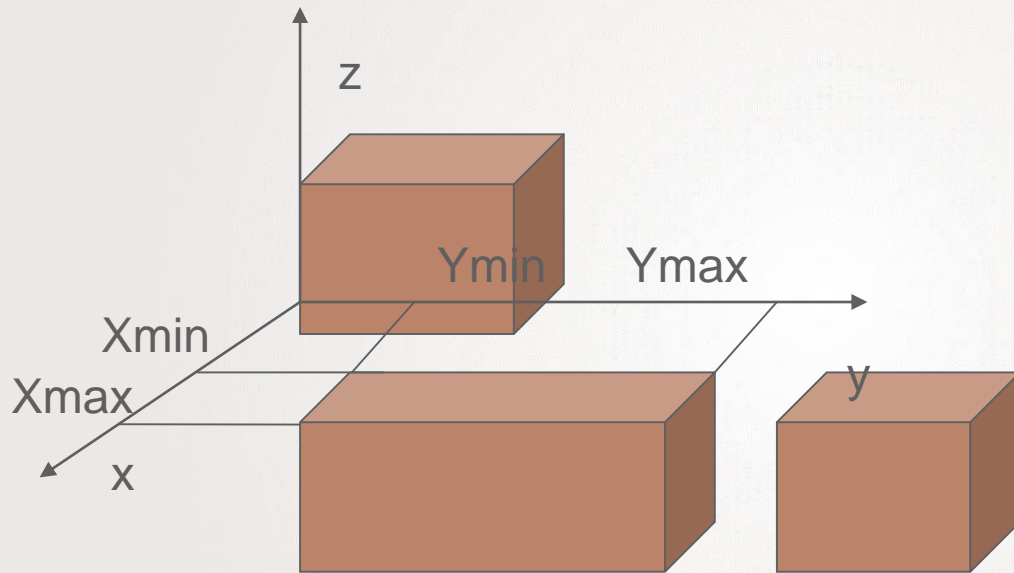
- o 6 numbers



- o Projections of the cube along x, y ,z direction.

# multiple cubes

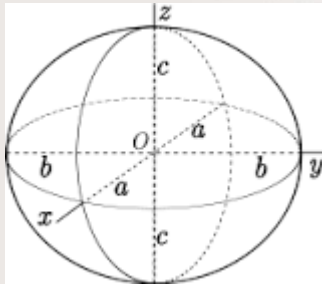
- o Different shape, need not be disjoint, can up to





# Ellipsoid

- define radii  $(a, b, c)$

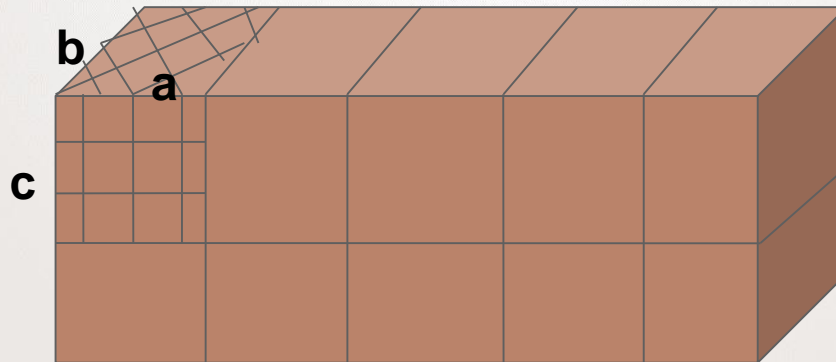


# And more highly customized...

- not built in function
- can be designed within the tool
- arrays, cylinders, etc

# Mesh

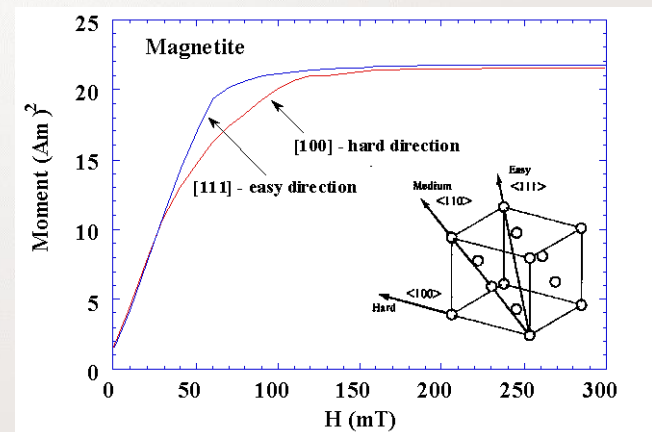
- define the discretization impressed on the simulation.
- creates an axes parallel rectangular mesh across the entire space.
- cell-based, with the center of the first cell one half step in from the minimal extremal point.



# Anisotropy Energy

- In physics, a ferromagnetic material is said to have magnetocrystalline anisotropy if it takes more energy to magnetize it in certain directions than in others.
- 'Easy axis' = takes no energy to magnetize along that direction.
- Uniaxial Anisotropy has one easy axis.
- Cubic Anisotropy has two easy axis.
- Inputs: **easy axis** and **anisotropy constant**.

$$E = KV(1 - \gamma^2) = KV \sin^2 \theta,$$



# Exchange Energy

- Exchange interaction is a quantum mechanical effect between identical particles.
- a wavefunction which describes the pair must be antisymmetric with respect to exchange of the electrons
- the difference in energy between aligned and anti-aligned configurations is what is called the exchange energy

# Exchange Energy

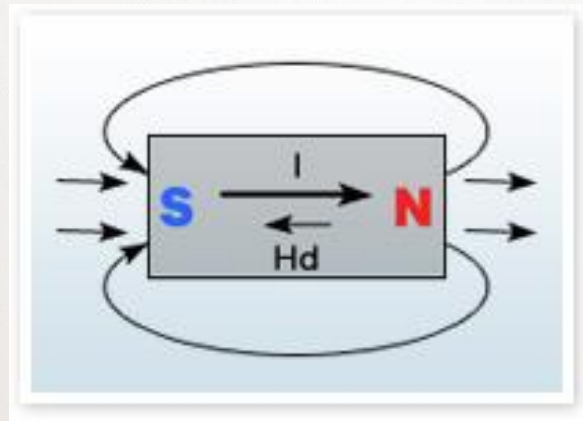
- Input: Exchange Constant

$$J_{ab} = \frac{1}{2}(E_+ - E_-) = \frac{J_{ex} - CB^2}{1 - B^4}$$

- C: Columbus integral, B: overlap integral,  $J_{ex}$ : exchange integral,  $J_{ab}$ : exchange constant,  $E_+/E_-$ : eigenvalues for the system energy.

# Demagnetization Energy

- The demagnetizing field, is the magnetic field generated by the magnetization in a magnet.
- The total magnetic field = demagnetizing field + any other field caused by free or displacement currents.



# Demag and Simple Demag

- Demag function assumes the magnetization is constant in each cell, and computes the average demagnetization field.
- Simple demag function does not use any of the of the symmetries inherent in the demagnetization kernel.

	Demag	Simple Demag
Source code	Complex	Simple
Performance	Ideal )	Poor (
Memory usage	Ideal)	Poor (



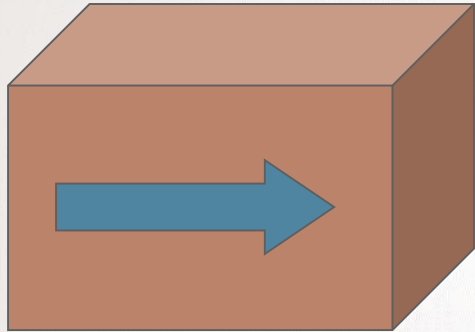
# Zeeman Energy

- Zeeman energy, or the external field energy, is the potential energy of a magnetised body in an external magnetic field.
- Two choices, time-invariant Zeeman energy and object-invariant Zeeman energy.

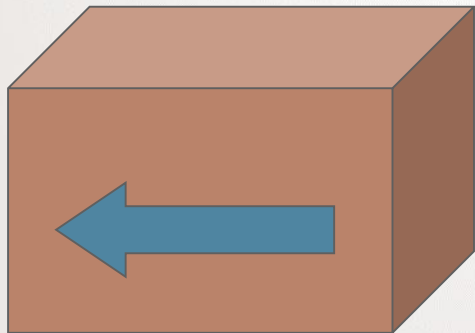
# Time-invariant Zeeman

- Energy does not change with respect to time
- Can be different with different objects

○  
objects.

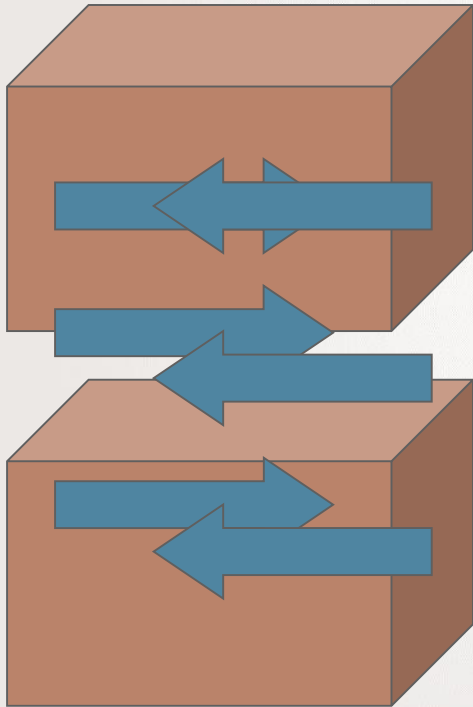


Inputs are the H field  
values for different



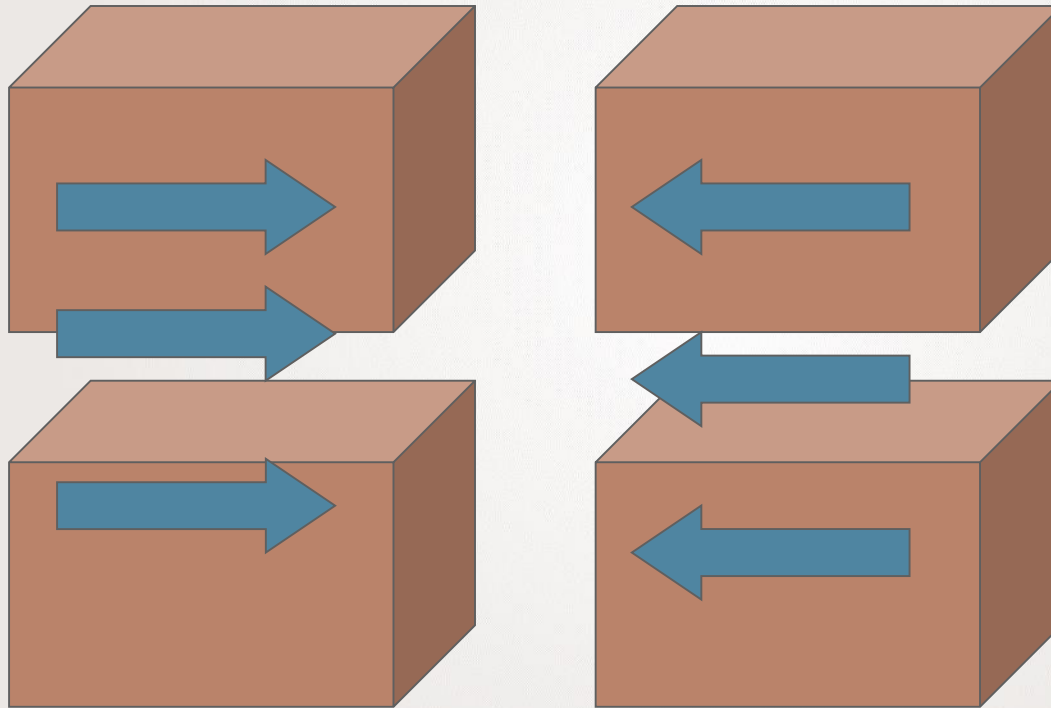
# Object-invariant Zeeman

- o Change with respect time (steps)



# Object-invariant Zeeman

- Inputs: 7 values for each energy sweep (energy changes its direction).



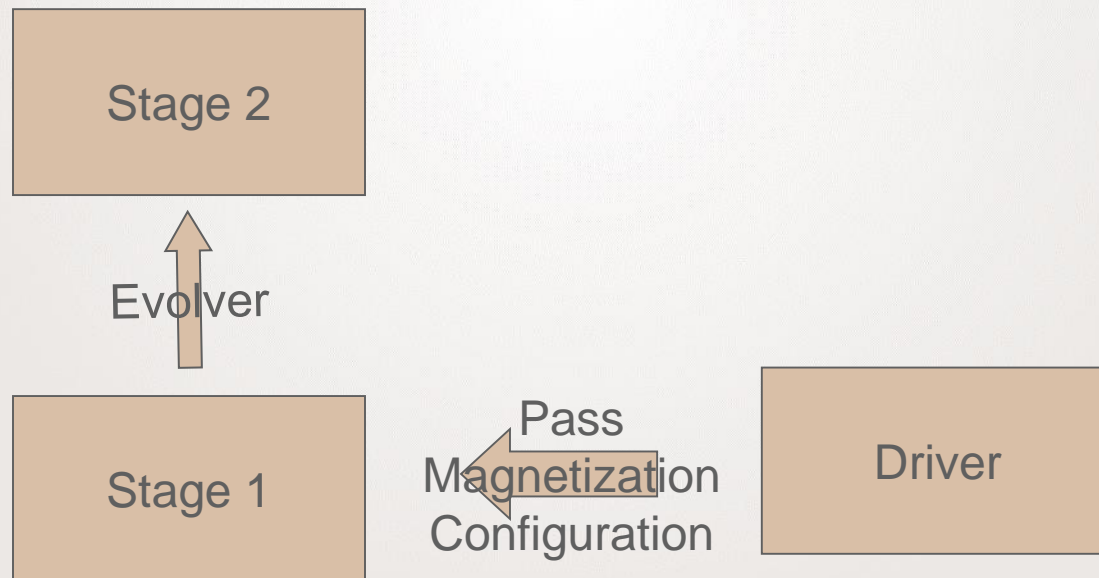
- $[1 \ 0 \ 0 \ -1 \ 0 \ 0 \ 5]$

# Evolver and Drivers

- Evolvers are responsible for updating the magnetization configuration from one step to the next.
- time evolvers - Landau-Lifshitz-Gilbert dynamics
- minimization evolvers, which locate local minima in the energy surface through direct minimization techniques.
- Evolvers are controlled by drivers and must be matched with the appropriate driver type

# Evolvers and Drivers

- The drivers hand a magnetization configuration to the evolvers with a request to advance the configuration by one step
- The drivers determine when a simulation stage or run is complete



# Evolvers & Drivers

	Evolvers	Drivers
Time Evolver	Euler Evolver	Time Driver
	Runge-Kutta Evolver	Time Driver
Min Evolver	CG Evolver	Min Driver

# Evolvers

## ○ Euler Evolver

- A simple first order forward Euler method with step size control on Landau-Lifshitz ODE

## ○ Runge-Kutta Evolver

- Uses Runge-Kutta methods
- in most cases, it will greatly **outperform** the Euler Evolver

## ○ CG Evolver

- in-development conjugate gradient minimizer
- Different algorithm, compare



# Drivers

- evolvers are responsible for moving the simulation forward in individual steps
- drivers coordinate the action of the evolver on the simulation as a whole, by grouping steps into tasks, stages and runs.
- Takes two inputs:
  - initial configuration for the magnetization unit spins
    - initial direction for the magnet.
  - Pointwise Saturation Magnetization
    - The state when an increase in external H field does not increase the magnetization further.

# References

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